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# **Dominance-based Matrix algorithm for Knowledge Reductions in Incomplete Fuzzy System**

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### *Abstract*

 *In this paper, definitions of knowledge granulation and rough entropy are proposed based on dominance relations in incomplete fuzzy system (fuzzy information system), and important properties are obtained. It can be found that using the definitions can measure uncertainty of an attribute set in the incomplete fuzzy information systems. A matrix algorithm for attributes reduction is acquired in the systems. An example illustrates the validity of this algorithm, and results of compared with other existing methods show that the algorithm is an efficient tool for data mining.* 

*Keywords: incomplete fuzzy information system, knowledge granulation, rough entropy, dominance matrix, knowledge reduction* 

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#### **1. Introduction**

The rough set theory proposed by Pawlak in 1982 [1] is a new mathematical tool to deal with the uncertain, vague, inaccurate information. Classic rough set theory built on equivalence relation (reflexive, symmetric, transmission) mainly solves the problem of incomplete information system. However; the vast majority of the information is incomplete, vague in reality. In order to get a broader application of the rough set theory, many scholars improved methods for incomplete information system [2-4]. For fuzzy information system, some researchers have suggested some improvement methods [5-8]. A lot of information in real problem is not only of incomplete, vague, and with preference relations. Greco, etc. [9-11] firstly introduced dominance relation into rough set model and fuzzy rough set, but they can only handled complete information. To this end, Wei et al [12] expanded the dominance relation to incomplete fuzzy information systems. Soon, they proposed rough fuzzy set in incomplete fuzzy information system based on similarity dominance relation [13].

This study aims to IFIS, the incomplete fuzzy information system. There have been unknown attribute values. We believe that the unknown attribute values are only missing, but it is also real. In other words, it is the fact that inaccurate knowledge forcing people to deal with only some of the information, incomplete information system. Each individual object has complete information on the potential. At present it is only just missed out these values. Therefore, in IFIS, the unknown attribute values can be considered as any other known attribute values are comparable. According to this explanation, using the extended dominance relations, a fuzzy rough set model is built into IFIS. Based on this fuzzy rough set model, we address knowledge granulation and rough entropy of rough set in IFIS, thus to knowledge reduction.

In next section, IFIS and its extended dominance relations are reviewed. Knowledge granulation is defined. In Section 3, after giving knowledge reduction algorithm based on dominance matrix, an example shows all reducts are enumerated by the matrices associated with IFIS. The following results of experiments were given by Section 4, Finally, we describe conclusions in Section 5.

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### **2. Basic Notions**

A fuzzy information system is the 4-tuple *S*=<*U*,*AT*,*V*,*f*>,where *U*– is a nonempty set, called the universe, *AT* – is a finite set of fuzzy attributes, *V*– is a set of fuzzy (linguistic) values of attributes,  $V=V_{AT}=\bigcup_{a\in AT}V_a$ ,  $V_a$  is the set of linguistic values of an attribute  $a\in AT$ ,  $f -$  is an

information function, *f*: *UAT*[0,1], *f*(*x*,*a*)∈[0,1] for every *x*∈*U* and every *a*∈*AT*.

In practice, we use fuzzy decision tables, which constitute a special form of fuzzy information systems with two disjoint groups of condition and decision attributes, respectively.

When the precise values for some of the objects on some fuzzy attributes are not known, i.e. unknown values (symbol "\*" is used to express unknown value), then such a fuzzy system is referred to as an incomplete fuzzy information system (IFIS). In this paper, an IFIS are still recorded as  $S = \langle U, AT, V, f \rangle$ , at this time  $V = [0,1] \cup \{^*\}$ .

Table 1 is an IFIS, of which  $U = \{x_1, x_2, ..., x_{10}\}$ , attribute set  $AT = \{a_1, a_2, a_3, a_4\}$ .



In IFIS, we believe that the unknown attribute value is only missing, but they actually exist, and therefore these unknown values can be combined with any other attribute value for comparison. According to this understanding, the dominance relation can be constructed as follows.

**Definition 1:** Let *S*=<*U*,*AT*,*V*,*f*> be an IFIS,*BAT*. The dominance relation in terms of *B* is defined as:

$$
R_B^{\geq} = \{(x, y) \in U^2 \mid \forall a \in B, f(x, a) \geq f(y, a) \lor f(x, a) = * \lor f(y, a) = *\} \tag{1}
$$

 $[x_i]_B^{\geq}$  is called a dominance class of object  $x_i$ , if:

$$
[x_i]_B^{\geq} = \{x_j \in U \mid (x_j, x_i) \in R_B^{\geq}\} = \{x_j \in U \mid \forall a \in B, f(x_j, a) \geq f(x_i, a) \vee f(x_i, a) = * \vee f(x_j, a) = *\}
$$
 (2)

$$
U/R_B^{\geq} = \{ [x_i]_B^{\geq} \mid x_i \in U \}
$$
\n(3)

 $U/R^{\geq}_{B}$  is a classification for the object set on the attribute set *B*.

In terms of dominance classes of *B*, the pair of lower and upper approximation operators can be defined by:

$$
R_B^{\geq}(X) = \{x_i \in U \mid [x_i]_B^{\geq} \subseteq X\}
$$
\n(4)

$$
\overline{R_B^{\geq}}(X) = \{x_i \in U \mid [x_i]_B^{\geq} \cap X \neq \emptyset\}
$$
\n
$$
(5)
$$

An element  $x \in U$  belongs to the lower approximation of X if all its dominance elements belong to *X*. It belongs to the upper approximation of *X* if at least one of its dominance elements belongs to *X*.

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As same as Pawlak approximation space, it is also to have many similar properties. For details, please refer to literature [11].

**Example 1:** Table 1 gives an IFIS. As a result, by the definition of the dominance relation, we have  $[x_1]_{4T}^2 = {x_1}$ ,  $[x_2]_{4T}^2 = {x_1, x_2, x_6}$ ,  $[x_3]_{4T}^2 = {x_3, x_8, x_0}$ ,  $[x_4]_{4T}^2 = {x_4, x_8, x_{10}}$  $[x_1[x_2]_{4T}^2 = {x_3, x_9}, [x_6]_{4T}^2 = {x_4, x_6, x_9}, [x_7]_{4T}^2 = {x_4, x_5, x_7, x_9}, [x_8]_{4T}^2 = {x_8}, [x_9]_{4T}^2 = {x_9}$  $,[x_{10}]_{4T}^{\geq} = \{x_1, x_{10}\}$ .

Furthermore, if  $A = \{a_1, a_2, a_3\}$ ,  $B = \{a_1, a_2\}$  then  $[x_1]_A^2 = [x_2]_A^2 = \{x_1, x_2, x_6\}$ ,  $[x_3]_A^2 = \{x_1, x_2, x_3, x_5, x_6, x_8, x_9\}, [x_4]_A^2 = \{x_1, x_4, x_8, x_{10}\}, [x_5]_A^2 = \{x_5, x_9\}, [x_6]_A^2 = \{x_4, x_6, x_9\},$  $[x_7]^2 = \{x_4, x_5, x_7, x_9\}$ ,  $[x_8]^2 = \{x_1, x_8\}$ ,  $[x_9]^2 = \{x_9\}$ ,  $[x_{10}]^2 = \{x_1, x_{10}\}$ , as well  $as[x_1]^2_B =$  $[x_2]_B^2 = \{x_1, x_2, x_6, x_8\}, \qquad [x_3]_B^2 = \{x_1, x_2, x_3, x_5, x_6, x_8, x_9\}, \qquad [x_4]_B^2 = \{x_1, x_4, x_8, x_{10}\},$  $[x_{5}]_{B}^{\geq} = \{x_{1}, x_{2}, x_{3}, x_{5}, x_{6}, x_{8}, x_{9}\},$ <br> $[x_{6}]_{B}^{\geq} = \{x_{1}, x_{2}, x_{4}, x_{6}, x_{8}, x_{9}, x_{10}\},$  $[x_7]_R^2 = \{x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9, x_{10}\},\qquad [x_8]_R^2 = \{x_1, x_8\},\qquad [x_9]_R^2 = \{x_1, x_8, x_9\},\qquad [x_9]_R^2 = \{x_1, x_9, x_{10}\},\qquad [x_9]_R^2 = \{x_1, x_2, x_{10}\},\qquad [x_9]_R^2 = \{x_1, x_{10}, x_{11}\},\qquad [x_9]_R^2 = \{x_1, x_{11}, x_{1$  $[x_{10}]_{B}^{\geq} = \{x_1, x_{10}\}\.$ 

In this section, knowledge granulation and rough entropy in an IFIS are introduced. They have some very useful properties. The relationship between knowledge granulation and rough entropy in IFIS is established.

**Definition 2:** The granulation of knowledge  $B \rightarrow A$ T is defined as follows, for an IFIS *S*=<*U*,*AT*,*V*,*f*>

$$
GK (B) = \sum_{i=1}^{n} \frac{|[x_{i}]_{B}^{2}|}{|U|^{2}}
$$
 (6)

**Example 2:** For example 1, one can calculate the knowledge granulation of knowledge *A* and *B*:

*GK*(*A*)=1/100(3+3+7+4+2+3+4+2+1+2)=0.31,*GK*(*B*)=1/100(4+4+7+4+7+7+10+2+3+2) =0.50.

#### **3. Algorithm**

**Definition 3:** Let *S*=<*U*,*AT*,*V*, $f$ > be an IFIS, *BAT*, *U*={*x<sub>1</sub>*,*x*<sub>2</sub>,...,*x<sub>n</sub>*}.The dominance matrix of system *S* with respect to *B* is defined as:

$$
M_{B} = (m_{ij})_{n \times n} = \begin{cases} 1, & x_{j} \in [x_{i}]_{B}^{\ge} \\ 0, & others \end{cases}
$$
   
  $i,j=1,2,...,n.$  (7)

*MB* is also called *l* level dominance matrix of *S* if |*B*|=*l*.

**Definition 4:** The intersection of the dominance matrices  $M_B$  and  $M_C$  is defined as follows, for any *B*, *C*<sub>*C*</sub> $AT$  on the *S*= $<$ *U*, $AT$ , *V*,  $f$ >,

$$
M_B \bigcap M_C = (m_{ij})_{n \times n} \bigcap (m_{ij})_{n \times n} = (\min\{m_{ij}, m'_{ij}\})_{n \times n}
$$
(8)

**Property 1:** Given S=<*U,AT,V,f*> and *B,C<sub></sub>* $\subseteq$ *AT,* if  $M_B$ , $M_C$  are two dominance matrices, we have that:

 $(m_{ii} = 1, i=1, 2, ..., n)$ (2) if *B*,  $C \subseteq AT$ , then  $M_{B \cup C} = M_{B} \cap M_{C}$ . Property 1can be obtained directly from Definition 3 and 4.

**Definition 5:** Let *S*=<*U,AT,V,f*> be an IFIS, *B*<sub> $\subseteq$ </sub>*AT*, a dominance matrix  $M_B$  with *B*.| $M_B$ | is the dominance cardinality of *B* if it indicated that the number of non-zero elements, that is, a total number of 1 values.

**Theorem 1:** Let S=\hat{r} be an IFIS; 
$$
B \subseteq AT
$$
. Then  $|M_B| = \sum_{i=1}^n |[x]_B^2|$ ,  
\n
$$
GK(B) = \frac{1}{|U|^2} |M_B| \qquad (9)
$$

**Proof:** According to the definition of the dominance matrix, for  $B \subseteq A T$ , we have that  $(m_{i_1}, m_{i_2}, \cdots, m_{i_n})$  corresponds to  $(x'_{i_1}, x'_{i_2}, \cdots, x'_{i_n}) = [x_i]_B^{\geq}$ , where  $\overline{\mathcal{L}}$  $\vert$  $\left\{ \right.$  $\sqrt{ }$ Ø  $x_{i} = \begin{cases} x_{i}, & x_{j} \in [x_{i}]_{E}^{2} \end{cases}$ *others*  $x'_{i_k} = \begin{cases} x_j, & x_j \in [x_i]_B^2 \\ \varnothing, & others \end{cases}$ ,  $x_j \in [x_i]_B^{\geq}$ 

Therefore,  $|M_B| = \sum_{i=1}^n |[x]_E^2$  $\sum_{i=1}^n \left| \left[ \, x \, \right]_B^z \right|$  . It holds that  $GK \left( B \right) = \frac{1}{\left| U \right|^2} \Big| {M}_{B} \Big|$  . This completes the proof. $\Box$ 

**Definition 6:** Given two *n*-dimensional  $n \times 1$  vectors  $\alpha = (e_1, e_2, \dots, e_n)^T$  and  $\beta = (b_1, b_2, \dots, b_n)^T$ , *T* said the transpose,  $\alpha$  is smaller than  $\beta$  if  $e_i \le b_i$  (*i*=1,...,*n*).

**Definition 7:** Let  $M_A = (\alpha_1, \alpha_2, \cdots, \alpha_n)^T$  and  $M_B = (\beta_1, \beta_2, \cdots, \beta_n)^T$  be a matrix, where  $\alpha_i$  and  $\beta_i$  (*i*=1,...,*n*) are *n*-dimensional *n*×*1* vectors.  $M_A$  is smaller than  $M_B$  if  $\alpha_i \leq \beta_i$  $(i=1,...,n)$ , denoted  $M_A \leq M_B$ .

**Definition 8:** Let  $S = \langle U, AT, V, f \rangle$  be an IFIS.  $B \subseteq AT$  is a reduct of  $AT$  if  $GK(B) = GK(AT)$ . If there is not  $b \in B$  makes  $GK(B-\{b\})=GK(AT)$ , claimed that *B* is one of the maximum reduct about *AT*.

Let *S*=<*U*,*AT*,*V*, $f$ > be an IFIS, *U*={ $x_1, x_2, ..., x_n$ }, *AT*={ $a_1, a_2, ..., a_m$ }, *B* $\subseteq$ *AT*,  $M_B = (\beta_1, \beta_2, \cdots, \beta_n)^T$  and  $M_{AT} = (\gamma_1, \gamma_2, \cdots, \gamma_n)^T$ . Based on the idea of the above subsection, a greedy algorithm for computing reduct can be constructed.

$1$ able $2.$ All $11$ to for Example.						
	a <sub>1</sub>	a <sub>2</sub>	$a_3$	a,		
$X_1$	0.1	0.2	0.1	0.1		
x <sub>2</sub>	0.1	$\star$	0.3	0.1		
$X_3$	0.3	0.2	0.3	$\star$		
$X_4$	0.1	0.2	$\star$	0.1		
$X_5$	$\star$	0.2	0.1	0.3		
$X_6$	0.3	0.1	$\star$	0.3		
X <sub>7</sub>	0.3	0.2	$\star$	$\star$		
$X_8$	0.3	0.1	0.2	0.3		
X <sub>9</sub>	0.2	0.3	$\star$	0.2		

Table 2. An IFIS for Example.

#### **Algorithm for calculating reduct:**

Input: IFIS *S*=<*U*,*AT*,*V*,*f*>.

Output: One reduct *B* of *AT*.

*Step 1.* Compute the dominance matrix  $M_{AT} = (y_1, y_2, \dots, y_n)^T$  of AT.

*Step 2.* Compute the first level matrix for every  $a_i ∈ AT(1≤/≤m)$ :

 $\bm{M}_{\{a_l\}} = \bm{M}_{\{a_l\}}^{(1)} = (\tau_1^{(1)}, \tau_2^{(1)}, \cdots, \tau_n^{(1)})^T$ (1) 1  $\mathcal{L}_{\{a_i\}} = M_{\{a_i\}}^{(1)} = (\tau_1^{(1)}, \tau_2^{(1)}, \cdots, \tau_n^{(1)})^T$ . For *i= 1* to *n* do If  $0 \neq \tau_i^{(1)} \leq \gamma_i$ , then let  $\tau_i^{(1)} = 0$ , and the new matrix is denoted by  $FM_{\{a_i\}}^{(1)}$ ,  $FM_{\{a_i\}}^{(1)}$  $(\tau_1^{(1)},\tau_2^{(1)},\cdots,\tau_n^{(1)})^T$  $(\tau_1^{(1)}, \tau_2^{(1)}, \cdots, \tau_n^{(1)})^T$  ,  $a_l \in AT(1 \leq l \leq m)$  is called the first-level reduct matrix; Come into the next step.

*Step 3.* If  $FM_{\{a_i\}}^{(1)}$  =0 then output a first-level reduct  $\{a_i\}$ .Otherwise, enter the next step.

*Step 4*. All second-level dominance matrices are obtained by intersection of the non-0 first-level reduct matrices on Step 2:  $\,M_{\,\{a_{I}a_{s}\,\}}^{(2)}$  ,  $M_{\,\{a_{I}a_{s}\,\}}^{(2)}$   $\neq$   $M_{\,\{a_{I}\,\}}^{(1)}$  $M_{\{a_l a_s\}}^{(2)} \neq M_{\{a_l\}}^{(1)}, M_{\{a_l a_s\}}^{(2)} \neq M_{\{a_s\}}^{(1)}$  $M_{\{a_{a},a_{s}\}}^{(2)} \neq M_{\{a_{s}\}}^{(1)}$ ,  $\neq$  s,  $l$ , s=1,2,...,n. Find all of the second-level reducts by the method used in *Step 2*.

*Step 5.* Repeat *Step 4* to obtain to the third-level and more reducts, until  $M_B^{(k)} = 0$ (1*≤k≤m*),*BAT*.

The time complexity of this algorithm is  $O(|U|^2 2^{|A|})$ .

**Example 3:** Table 2 provides an IFIS *S*=<*U*,*AT*,*V*,*f*>, where *U*={*x1*,*x2*,*x3*,*x4*,*x5*,*x6*,*x7*,*x8*,*x9*}, *AT*={*a1*,*a2*,*a3*,*a4*}. We run our matrix algorithm on Table 2 in this subsection, to demonstrate its simplicity, practicability and time efficiency.

Step 1: Construct the dominance matrices.



Steps 2 and 3: Construct the first-level reduct matrices and output reduction.

Compare their rows of  $M_{a_1}, M_{a_2}, M_{a_3}$  and  $M_{a_4}$  to  $M_{AT}$ 's. Find that there is no  $0 \neq \tau_i^{(1)} \leq \gamma_i$ . Row 1,4 and 5 are same for  $M_{\{a_2\}}$  and  $M_{AT}$ . Row 2 is same for  $M_{\{a_3\}}$  and  $M_{AT}$ . Row 6 and 8 are same for  $M_{AAT}$  and  $M_{AT}$ . Therefore, we can see that there is no firstlevel reduct.

Thus, the first-level reduction matrices are:

	111111111		000000000		111111111
$FM.$ <sup>(1)</sup> $\{a_1\}$	111111111		111111111		0000000 0 0
	001011110		111110101		011101101
	111111111		000000000		111111111
	111111111	$FM(1)$ .	000000000	$FM(1)$ .	111111111
	001011110	$\{a_2\}$	111111111	$\{a_3\}$	111111111
	001011110		111110101		111111111
	001011110		111111111		011101111
	00 10 11 11 1		010000001		111111111
	111111111				
	111111111				
	111111111				
$FM_{\scriptscriptstyle{\{a_4\}}}$	111111111				
	000000000				
	000000000				
	111111111				
	000000000				
	001011111				

Step 4 and 5: Get the second-level and more dominance matrices, reduction.

 $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$ 

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 00 00 0000 1 00 1 0 11110 00 1 0 10100 00 1 011110 000 000000 000 000000 001 0 10100 111111111 00000000 0 (1) { } (1) { } (2) { , } <sup>1</sup> <sup>2</sup> <sup>1</sup> <sup>2</sup> *M <sup>a</sup> <sup>a</sup> FM <sup>a</sup> FM <sup>a</sup>* (1) { } (1) { } (2) { , } *a*<sup>1</sup> *a*<sup>3</sup> *a*<sup>1</sup> *a*<sup>3</sup> *M FM FM* 00 1 0 11111 00 1 0 0 111 0 00 1 0 1111 0 001 0 1111 0 111111111 111111111 0010 0 11 0 1 0000000 0 0 111111111 00 10 0 1111 0000 0000 0 00 101111 0 00000000 0 00000000 0 111111111 001 0 11110 111111111 111111111 (1) { } (1) { } (2) { , } <sup>1</sup> <sup>4</sup> <sup>1</sup> <sup>4</sup> *M <sup>a</sup> <sup>a</sup> FM <sup>a</sup> FM <sup>a</sup>* 0 10000 0 0 1 0 111 0 1111 111 11 0 1 0 1 111111111 00000000 0 00000000 0 011 100101 000000000 000000000 (1) { } (1) { } ( 2 ) { , } <sup>2</sup> <sup>3</sup> <sup>2</sup> <sup>3</sup> *M <sup>a</sup> <sup>a</sup> FM <sup>a</sup> FM <sup>a</sup>* 0000000 0 1 000000 0 0 0 11111 0 1 0 1 000 0000 0 0 0000000 0 0 00000000 0 11111 0 1 0 1 111111111 000000000 (1) { } (1) { } ( 2) { , } *a*<sup>2</sup> *a*<sup>4</sup> *a*<sup>2</sup> *a*<sup>4</sup> *M FM FM* 0 0 1 0 11111 0000 0000 0 111111111 0000000 0 0 000000 00 0 111111111 011 1 0 1101 00000000 0 111111111 (1) { } (1) { } ( 2) { , } *a*<sup>3</sup> *a*<sup>4</sup> *a*<sup>3</sup> *a*<sup>4</sup> *M FM FM*

Compared with  $M_{AT}$ , there is no second-level reduct. By using the same method we can get  $\mathit{FM}_{\{a_1, a_2, a_3\}}^{(2)}$ . Each row of  $\mathit{FM}_{\{a_1, a_3, a_4\}}^{(2)}$  are 0. The looping can now be stopped.

Therefore, we can see that a reduct of  $AT$  is  $\{a_1, a_2, a_3\}$ .

As can be seen from the discussed above, obtaining reducts from a large data table for even very complex one, is a relatively easy task.

#### **4. Results of Experiments**

In Table 3-7 results of experiments on six well-known data sets from the UCI Machine Learning Repository [14] are cited. The Matrix and Revised-quickreduct algorithm [15] have been implemented using MATLAB for the databases. Before the experiment, we done the preprocessing that the data is limited to between 0-1.

From the table, it is evident that Matrix algorithm produces minimal reduct for large data sets with more number of attributes. The performance analysis of the Matrix and the Revised-quickreduct is also depicted in Figure 1-5. (Note,at.=attributes,mv.=missing values, Mx.=Matrix )

Table 3. Comparative Analysis of Indiscernibility Relation Method

Data set	Instances	No.of at.	No.of my.	Mx.	Revised-quickreduct
Car	8		5		
Hepatitis	155	19	167	5	6
Heart (Switzerland)	123	13	273	5	4
Soybean (Large)	307	35	705		13
Water-treatment-data	527	38	591		
Rchocardiogram	74	13	132	3	

#### Table 4. Comparative Analysis of Mean Imputation 1



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Data set	Instances	No of at.	No of my.	Mx.	Revised-quickreduct
Car			5		
<b>Hepatitis</b>	155	19	167	5	
Heart (Switzerland)	123	13	273	6	
Soybean (Large)	307	35	705		12
Water-treatment-data	527	38	591		
Rchocardiogram	74	13	132		

Table 5. Comparative Analysis of Mean Imputation 2

Table 6. Comparative Analysis of Median Imputation

Data set	Instances	No.of at.	No of my.	Mx.	Revised-aujckreduct	
Car	8		5			
<b>Hepatitis</b>	155	19	167	5		
Heart (Switzerland)	123	13	273	6		
Soybean (Large)	307	35	705		12	
Water-treatment-data	527	38	591	5		
Rchocardiogram	74	13	132			

Table 7. Comparative Analysis of Mode Imputation





Figure 1. Performance analysis of the Matrix and the Revised Quickreduct (Indiscernibility)



Figure 2. Performance Analysis of the Matrix and the Revised Quickreduct (Mean Imputation1)



*Dominance-based Matrix algorithm for Knowledge Reductions in Incomplete… (Lixin Fan)* 



Figure 5. Performance Analysis of the Matrix and the Revised Quickreduct (Mode)

#### **5. Conclusion**

IFIS is a special information system with both fuzzy knowledge and uncertainty. In this paper, it gives a new definition of some basic concepts of rough set in IFIS by dominance relation. On this basis, we studied the IFIS knowledge granularity and advantages matrix, made some important conclusions. A IFIS attribute reduction algorithm based on the dominance matrix is built. The next step will be to use the knowledge reduction algorithm to obtain fuzzy rules, decision analysis.

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