# Numerical investigation of V shaped three elements resonator for optical closed loop system

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#### ABSTRACT

This study have outlined numerical investigation of V shaped three element resonator. The stability parameter is measured against back mirror curvature radius, back mirror phase angle, focusing length, focusing mirror phase angle, folding range in both S plane and T plane. The stability parameter is changed in positive and negative trend under the operating system parameters. The stability parameter should be optimized in order to achieve high performance efficiency of resonator system. Beam radius variations are also measured versus focusing range, folding range, and back mirror phase angle. It is clear that the negative effects of increasing system parameters on beam radius variation in both S plane and T plane.

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#### 1. INTRODUCTION

Three are many types of resonators system that are namely T shaped and V shaped according to its applications [1-2]. The basic concepts for resonator systems are back mirror with curvature radius and alpha phase angle variations [3-4]. The folding range is the separation between back mirror and focusing mirror. In many studies the focusing mirror with curvature radius ranges from 100 mm to 300 mm and alpha phase angle variations from one degree to seven degree in many applications. [5-6]. The difference between focusing mirror and output flat mirror id the space length which is taken from 50 mm to 300 mm in many research applications [7-9].

Many attempts in other studies for optimization of the stability parameter over the operation parameters of back mirror curvature radius [10-13], back mirror phase angle, focusing length, focusing mirror phase angle, folding range in both S plane and T plane [14-17]. Many papers study the beam radius variations are also measured versus focusing range, folding range, and back mirror phase angle for short applications [18-20].

#### 2. MODEL DESCRIPTION AND RESEARCH METHOD

Figure 1 shows the basic schematic view of v shaped three elements resonator. The system consists of back mirror with curvature radius variations in mm units and alpha phase in degree. L-foc is the focusing

range from back mirror to focusing mirror. M-foc represents the focusing mirror with curvature radius variations in mm units and alpha phase in degree. L is the space length and expressed in mm units.



Figure 1. Basic schematic view of three element resonator

M-out is the output mirror and in the difference of focusing mirror by the space length (L). The back mirror curvature radius variations from 10 mm to 30 mm and its phase ranges from 1 degree to 20 degree. The focusing ranges from 10 mm to 60 mm. The focusing mirror curvature radius variations from 100 mm to 300 mm with a step size of 50 mm. and its alpha phase ranges from 5 degree to 30 degree.

#### 3. RESULTS AND ANALYSIS

We have analyzed V shaped three elements resonator under the operating parameters. The back mirror curvature radius variations from 10 mm to 30 mm and its phase ranges from 1 degree to 20 degree. The focusing ranges from 10 mm to 60 mm. The focusing mirror curvature radius variations from 100 mm to 300 mm with a step size of 50 mm. and its alpha phase ranges from 5 degree to 30 degree. It is observed from Figure 2 the variations of stability parameter against variations of back mirror curvature radius in both S and T planes. It is observed that as back mirror curvature radius increases, this leading to increasing of stability parameter in both S plane and T plane.



Figure 2. Variations of stability parameter against variations of back mirror curvature radius

Figure 3 shows the variations of stability parameter against variations of back mirror phase angle. It is indicated that stability parameter increasing in S plane with increasing of back mirror phase angle. As well as stability parameter decreasing in T plane with increasing of back mirror phase angle. Figure 4 presents the variations of Stability parameter in relation to focusing length variations. It is clear that as focusing length increases, this leading to increase of stability parameter in both S plane and T plane up to 40 mm focusing length. After 40 mm focusing length, the performance of stability decreases consequently.

Figure 5 shows the stability parameter variations in relation to curvature radius of focusing mirror variations. It is observed that the stability increases sequent up to 40 mm curvature radius of focusing mirror. The stability parameter is still constant and in steady state performance up to 50 mm curvature radius of focusing mirror phase angle. It is found that as focusing mirror phase angle increases, this results in increasing of stability parameter in S plane. But as focusing mirror phase angle increases, this results in decreasing of stability parameter in T plane. Figure 7 shows the variations of stability parameter against variations of folding range

or space length. It is clear that as folding range or space length increases, this results in decreasing of stability parameter in both T and S planes. The stability parameter degraded larger than in T plane than S plane.

As shown in Figure 8 the beam radius variations versus focusing range variations from 10 mm to 50 mm. It is observed that beam radius variations tend to decrease in both S plane and T plane. Beam radius variations in T plane is larger than S plane. As well as Figure 9 shows the beam radius variations in relation to variations of folding ranges from 0 mm to 300 mm. It is indicated that beam radius variations tend to decrease in both S and T planes. Beam radius variations in T plane is larger than S plane. As well as Figure 9 shows the beam radius variations tend to decrease in both S and T planes. Beam radius variations in T plane is larger than S plane up to 250 mm folding range. After 250 mm folding range the beam radius variations in S plane is larger than T plane. Beam radius at back mirror variations against back mirror phase angle variations as shown in Figure 10. It is clear that beam radius at back mirror decreases with increasing back mirror phase angle variations in only S plane and almost constant in T plane. Intermode beat frequency of the system is 419.877 MHz, Total cavity length is  $57(L_foc) + 300(L) = 357$  mm.



Figure 3. Variations of stability parameter against variations of back mirror phase angle



Figure 4. Stability parameter in relation to focusing length



Figure 5. Stability parameter in relation to curvature radius of focusing mirror



Figure 6. Variations of stability parameter against variations of focusing mirror phase angle



Figure 7. Variations of stability parameter against variations of folding range or space length



Figure 8. Beam radius variations versus focusing range variations



Figure 9. Beam radius variations in relation to variations of folding range



Figure 10. Beam radius at back mirror variations against back mirror phase angle variations

#### CONCLUSION 4.

In a summary, it is found that the intermode beat frequency of the resonator system is 419.877 MHz, with total cavity length is  $57(L_{foc}) + 300(L) = 357$  mm. It is observed that the positive and negative effects of increasing operating system parameters on the beam radius of resonator system efficiency. It is clear that the optimized beam radius is obtained with T plane. As well as it is observed that the optimized stability parameter is obtained with S plane. After 250 mm folding range the beam radius variations in S plane is larger than T plane. It is indicated that the beam radius variations in T plane is larger than S plane. Moreover the stability increases sequent up to 40 mm curvature radius of focusing mirror. The stability parameter is still constant and in steady state performance up to 50 mm curvature radius of focusing mirror

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Dr. IS Amiri has been doing research on several topics such as the optical soliton communications, laser physics, fiber lasers, fiber grating, electro-optical modulators, nanofabrications, semiconductor design and modelling, Lumerical modelling, plasmonics photonics devices, nonlinear fiber optics, optoelectronics devices using 2D materials, semiconductor waveguide design and fabrications, photolithography fabrications, E Beam lithography, quantum cryptography and nanotechnology engineering.



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