

Design and Implementation of Next Generation Automotive Theft Preventive System

K. Hema¹, Dr. Muralidharan²

¹Research Scholar, Department of Electrical and Electronics Engineering (Marine), AMET University, Chennai

²Mepco Schlenk Engineering College, Sivakasi

Article Info

Article history:

Received Jun 9, 2016

Revised Nov 20, 2016

Accepted Dec 11, 2016

Keywords:

Automotive

ARM

Cortex-M0

NXP

LPC11C14

ABSTRACT

In this paper, we proposed to design a next-generation auto theft prevention system by adding significant enhancements and modernizing the existing security features. As vehicles turn out to be more refined, vehicle security frameworks must be more grounded than at any other time. A current vehicle uses remote keyless passage framework and Immobilizer framework as the primary weaponry against vehicle robbery. These structures avoid unapproved access of the vehicle to a particular degree, however, are not a secure one. Because of the straightforward and imperfect nature of these security frameworks, auto burglary occurrences worldwide are on the ascent. This venture needs a low power microcontroller however with elite prerequisites. LPC11C14 from NXP Semiconductors addresses these issues and in this manner picked as the primary MCU. It is an ultra-low-power ARM Cortex-M0 based microcontroller that can run up to 50MHz. It has 32KB of Flash memory and 8KB RAM.

*Copyright © 2018 Institute of Advanced Engineering and Science.
All rights reserved.*

Corresponding Author:

K. Hema,

Research Scholar, Department of Electrical and Electronics Engineering (Marine),

AMET University, Chennai

1. EXISTING SYSTEM

Some of the major problems with the existing auto theft prevention system offer no protection when the key fob is stolen. So a brilliant key fob sold in the market is not keen. Vehicle GPS beacons won't have the capacity to find a vehicle in GPS denied conditions, for example, inside structures, underground and thick city areas, bringing about the loss of the vehicle. The at present utilized movement and tilt cautions will alarm the proprietor notwithstanding for an unexpected touch by a passing individual or a coincidental hit by a ball from a playing tyke. Restricted or to be an exact no of focal UI to arrange, alter the vehicle security framework.

2. INTRODUCTION

In Present days thefts in an automobile is increasing at a rapid rate. So to protect vehicles, we developed the system consists of GSM, GPS and MEMS Technology which is operated by using a low-cost microcontroller. It's very cheap and simpler compared to other antitheft vehicle locking systems. Tracking and classification of targets are primary concerns in automated surveillance and security systems. The tracking and classification information can be used for statistical purposes, i.e., counting the number of goals of a particular type and registration of their velocities and directions of arrival. In this work, we will focus on hard targets. Circularly polarized patch antennas are widely used in mobile satellite communication systems, radio-frequency identification systems, global positioning systems (GPS) and most vehicle communication devices. The typical GPS receiver uses a triangulation method to determine the position and velocity of a vehicle based on data transmitted by a GPS satellite. An on-vehicle GPS antenna requires right-handed

circular polarization, which enables a flexible orientation angle between the transmitter and receiver and reduces multipath reflections. Circular polarization waves are typically generated by using a feeding structure to excite two orthogonal linearly polarized modes of equal amplitude and with a 90° phase difference. Single-feed and dual-feed structures are commonly used in patch antennas. A well-known method of obtaining circular polarization using a single-feed patch antenna is by slightly perturbing the antenna structure at appropriate locations such as stubs, slits, notches, slots and truncated corners of the patch. Since the two near-degenerate orthogonal modes have equal amplitude and a 90° phase difference, the purity of polarization is relatively lower than that in the dual-feed structure. Compared to single feed patch antennas, those with a dual-feed structure provide a larger circularly polarized bandwidth but require a larger ground plane for the feeding network. In MEMS technology, one way of sensing metallic objects is by making use of their magnetic properties [4]. We know that metallic objects induce a magnetic field partly due to its permanently magnetized ferromagnetic content and partly due to the deflection of the earth magnetic field. This induced magnetic field can be measured with distributed passive magnetometers. For moving metallic vehicles, the magnetometer measurement will vary in time, which results in a time-dependent signal. Like in other standard tracking application based on radar, time difference of arrival and received signal strength, this signal depends on the position, speed, orientation and target specific parameters. Studies on Optical and Electrical Properties of Hafnium Oxide Nanoparticles is discussed in [6]. The difference between the applications is summarised in the sensor model that relates the quantities to the observations. The same motion models and filters can be used in all these applications. However, we do not focus on suggesting particular motion models, and filters, since these choices are standard in literature study of optical, surface morphological and electrical properties of manganese oxide nanoparticles, is explained in [7]. Instead, we focus on the application specific fundamental questions of observe ability and geometry for the sensor model. In this paper [8] describes that the An Efficient Self-Reconfiguration and Route Selection for Wireless Sensor Networks.

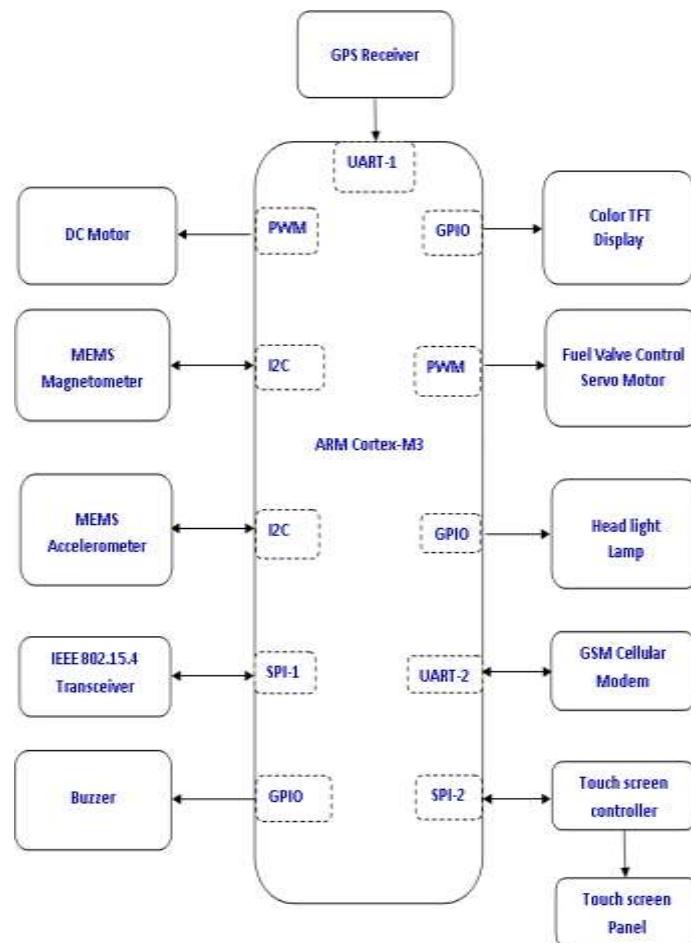


Figure 1. Overall Hardware Design of Vehicle Unit

3. FEATURES AND ITS DESCRIPTION

The Overall Hardware Design of Vehicle Unit as appeared in Figure 1. The accompanying modules are executed in this venture recorded beneath:

a) Smart Lock

The framework is furnished consequently when the driver moves far from the vehicle. It is incapacitated just when a particular motion is made in the hand-held remote key coxcomb. The 3D signal is produced in mid-air and can be reinvented by the client on the fly. The air signal is perceived utilizing a 3-pivot MEMS Accelerometer that detects the gravitational compels applied upon it [1]. A stolen key fob subsequently can't be used to go into the vehicle without playing out the mystery signal. The secret key is put away in an external non-unpredictable serial EEPROM memory.

b) Cryptographic Entry

If the signal is substantial the key fob as appeared in Figure 2 transmits a one of a kind encoded code that progressions each time when this motion is made. RC4 Stream Cipher Cryptographic calculation guarantees the wellbeing of the information transmitted. The key fob speaks with car vehicle unit utilizing IEEE 802.15.4 [9] remote systems administration convention. This keeps cheats from recognizing the static codes which were utilized as a part of more seasoned keyless passage frameworks. The remote parcels are likewise used to quantify the vicinity of the key fob to the vehicle.

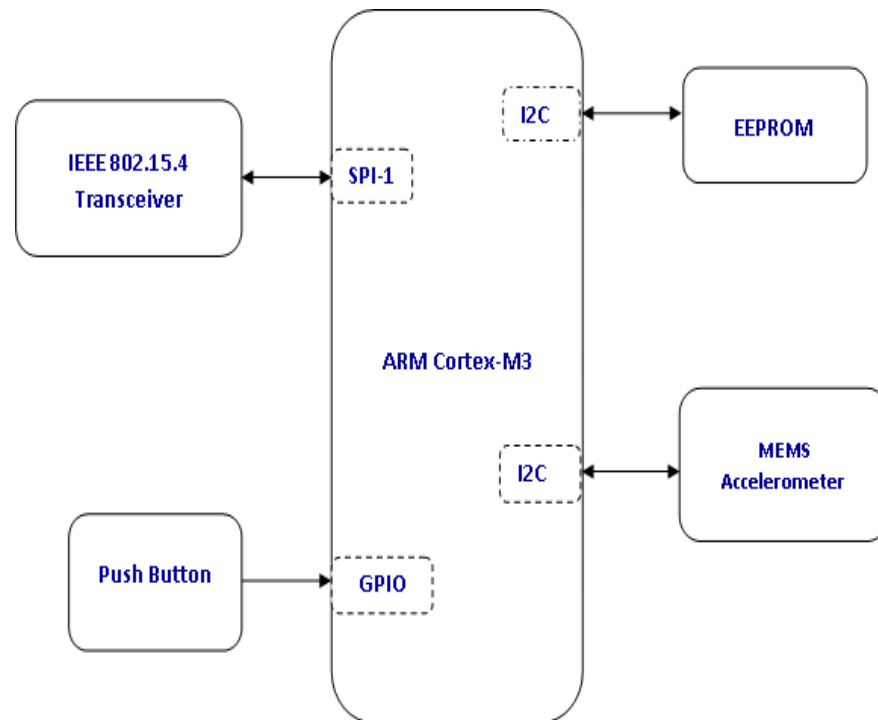


Figure 2. Smart Key fob Unit

c) Touch Ignition

A double layer keying methodology is taken after amid vehicle start prepare. This comprises of programming and equipment keys. An unusual touch signal is made on the 65K Colour Touchscreen TFT Display that goes about as the product key. The framework confirms this and after that acknowledges the equipment core which is the real key fob regularly utilized. This element can be incidentally incapacitated and empowered using SMS sent by the proprietor. This is valuable in the circumstances, for example, when somebody (like a repairman) other than the proprietor needs to deal with the vehicle and the proprietor does not need the other individual to know the mystery onscreen secret key. A serial EEPROM memory is utilized to store the watchword.

d) Motion Alarm

The vehicle unit always screens the vehicle movement after being furnished (bolted). The integrated movement detecting subsystem measures the vehicles three-dimensional position and recognizes any unapproved change if the vehicles are moved or tilted that surpasses an edge level [10]. The affectability of this capacity can be balanced on the Touchscreen show GUI to viably stay away from any false notices that are regular with existing vehicle security frameworks [11]. When somebody tries to break into the vehicle persuasively, the alert triggers the siren and head lights and sends an SMS to the proprietor.

e) Vehicle Tracking

GPS and GSM innovations empower the vehicle proprietors to track and screen the vehicle with PDA at whenever from anyplace. The immediate upgrade in this component is its capacity to illuminate the vehicle position notwithstanding amid a GPS blackout utilizing dead retribution strategy. This is accomplished with the assistance of Inertial Navigation Sensors that comprises of a 3-pivot MEMS Magnetometer and a 3-hub MEMS Accelerometer which will go about as a tilt repaid compass module.

f) Car Searcher

When the proprietor approaches the vehicle, the framework consequently confirms the code from the remote key and the vehicle produces a head light glimmer and horn beep to demonstrate its nearness [2]. This element is known as an auto discoverer, and it helps the proprietor to find the vehicle in a parking garage where a few vehicles are stopped.

g) GPS Fence

This element confines the vehicle development inside a particular territory. For instance, if the proprietor needs the auto to move just inside a particular city, once it moves out of city outskirts the proprietor would promptly get an SMS ready with regards to the present area of the vehicle. The fascinating element here is the client can modify the fence span in the Touchscreen show. This adaptability enables the client to set a virtual fence that can be at the building level, road level, city level or state level.

h) Fuel Cut-off

This component is precious particularly in the event of an auto robbery. On the off chance that the vehicle is some way or another hacked into and taken, you can send the message that will gradually remove the fuel supply, consequently impairing the vehicle. A Servo Motor controlled valve is utilized to cut the fuel supply.

4. CONCLUSION

In this work, we proposed a technique to offer insurance notwithstanding when the keyfob is stolen, and we call it the genuine brilliant keyfob. It enables us to track the vehicle even in GPS denied situations, for example, inside structures, underground and thick city locales. The present-day movement and tilt cautions will alarm the proprietor notwithstanding for an inadvertent touch by a passing individual or an incidental hit by a ball from a playing tyke. Our framework takes out this with movable movement alert affectability highlight. A focal UI to accumulate, modify the vehicle security framework, which is absent in the past vehicle plans. We unequivocally trust that these components without a doubt will accomplish best in the automotive.

REFERENCES

- [1] Speeter T H. *Transformation hand motion for telemanipulation*. Presence, 1992; 1(1); 63–79.
- [2] Zhang Lixia. *Intelligent parking system application maintenance*. University of electronic science and technology press. 2013; 03.
- [3] Rakijas M. *Magnetic object tracking based magnetic sensor measurements*. U.S. Patent 6 269 324; 2001.
- [4] Lenz J. *Magnetic sensors and their applications*. *IEEE Sensors*, 2006; 6(3); 631–649.
- [5] Oh and J K and Bang W C, et al. *Inertial sensor-based recognition of 3-D character gestures with an ensemble of classifiers*. Presented at the 9th Int. Workshop on Frontiers in Handwriting Recognition. 2004.
- [6] Jayaraman V, Sagadevan S and Sudhakar R. *Studies on Optical and Electrical Properties of Hafnium Oxide Nanoparticles*. *Journal of Electronic Materials*, 2017; 1-6.
- [7] Vijayamari A, Sadayandi K, Sagadevan S and Singh P. *A study of optical, surface morphological and electrical properties of manganese oxide nanoparticles*. *Journal of Materials Science: Materials in Electronics*, 2017; 1-8.
- [8] M.A. Manivasagam, T. Ananthan, 2017. An Efficient Self-Reconfiguration and Route Selection for Wireless Sensor Networks, *IJMSR*, 9(2), pp. 192-199.

-
- [9] Adeeb Salh, Lukman Audah, Nor Shahida M. Shah, Shipun A. Hamzah, 2017. Maximizing Energy Efficiency for Consumption Circuit Power in Downlink Massive MIMO Wireless Networks, *International Journal of Electrical and Computer Engineering (IJECE)*, 7(6), pp. 2977-2985.
- [10] Muhammad Anwar, Abdul Hanan Abdullah, Kashif Naseer Qureshi, Abdul Hakeem Majid, 2017, Wireless Body Area Networks for Healthcare Applications: An Overview, *TELKOMNIKA (Telecommunication Computing Electronics and Control)*, 15(3).
- [11] Marwa Mekki, Osman Abdallah, 2017. Development of a Wireless Sensors Network for Greenhouse Monitoring and Control, *Indonesian Journal of Electrical Engineering and Informatics (IJEI)*, 5(3).